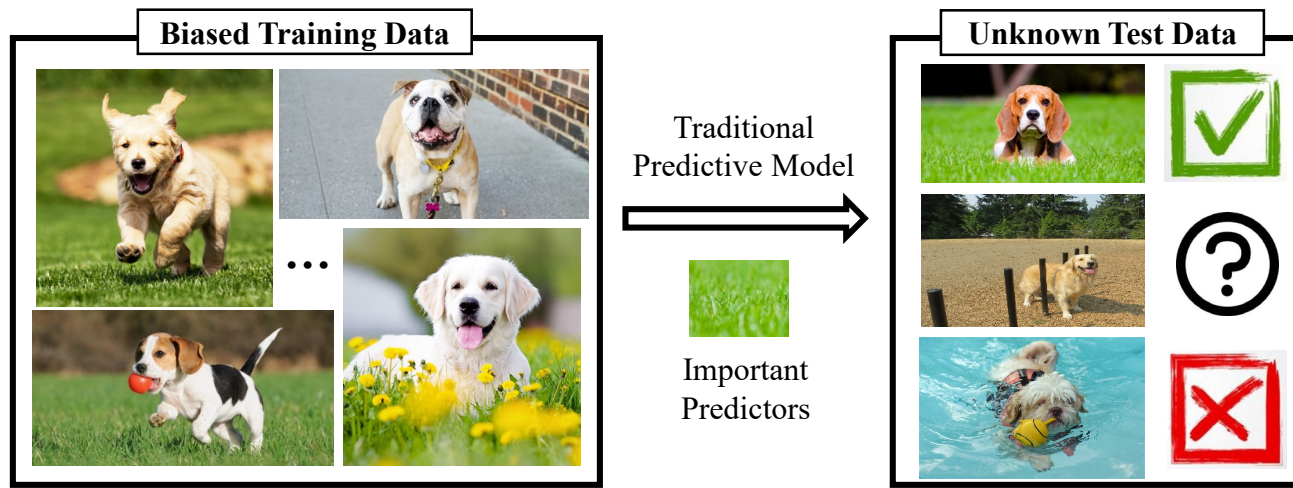


Stable Prediction with Model Misspecification and Agnostic Distribution Shift

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INTRODUCTION



Unstable prediction of traditional predictive model, **WHY?**

Model misspecification and correlation based

- Spurious correlation (**Unexplainable**)

Agnostic distribution shift

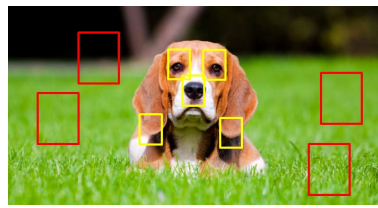
- Variant of spurious correlation (**Unstable**)

PROBLEM

Problem 1 (Stable Prediction) Given one training environment $e \in \mathcal{E}$ with dataset $D^e = (\mathbf{X}^e, Y^e)$, the task is to learn a predictive model to predict across unknown environment \mathcal{E} with not only small **Average_Error** but also small **Stability_Error**.

$$\text{Average_Error} = \frac{1}{|\mathcal{E}|} \sum_{e \in \mathcal{E}} \text{RMSE}(D^e), \quad (1)$$

$$\text{Stability_Error} = \sqrt{\frac{1}{|\mathcal{E}|-1} \sum_{e \in \mathcal{E}} (\text{RMSE}(D^e) - \text{Average_Error})^2}$$



Human like thinking: What cause the object to be a dog?

Suppose $X = \{S, V\}$, and the label $Y = f(S) + \epsilon$

We define S as **stable features** and V as **unstable features**

Assumption 1: $P(Y|S)$ is invariant across environments

Assumption 2: All stable features S are observed

Model misspecification: ignoring non-linear term $g(S)$

$$Y^e = f(\mathbf{S}^e) + \mathbf{V}^e \beta_V + \epsilon^e = \mathbf{S}^e \beta_S + g(\mathbf{S}^e) + \mathbf{V}^e \beta_V + \epsilon^e.$$

where $\beta_V = 0$ and $\epsilon^e \perp \mathbf{X}^e$.

$$\hat{\beta}_{VOLS} = \beta_V + \left(\frac{1}{n} \sum_{i=1}^n \mathbf{V}_i^T \mathbf{V}_i\right)^{-1} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{V}_i^T g(\mathbf{S}_i)\right) + \left(\frac{1}{n} \sum_{i=1}^n \mathbf{V}_i^T \mathbf{V}_i\right)^{-1} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{V}_i^T \mathbf{S}_i\right) (\beta_S - \hat{\beta}_{SOLS}), \quad (4)$$

$$\hat{\beta}_{SOLS} = \beta_S + \left(\frac{1}{n} \sum_{i=1}^n \mathbf{S}_i^T \mathbf{S}_i\right)^{-1} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{S}_i^T g(\mathbf{S}_i)\right) + \left(\frac{1}{n} \sum_{i=1}^n \mathbf{S}_i^T \mathbf{S}_i\right)^{-1} \left(\frac{1}{n} \sum_{i=1}^n \mathbf{S}_i^T \mathbf{V}_i\right) (\beta_V - \hat{\beta}_{VOLS}), \quad (5)$$

$\hat{\beta}_{VOLS}$ is biased if $\mathbb{E}(\mathbf{V}^T g(\mathbf{S})) \neq 0$ or $\mathbb{E}(\mathbf{V}^T \mathbf{S}) \neq 0$ in Eq. (4), leading to the biased estimation on $\hat{\beta}_{SOLS}$ in Eq. (5)

Spurious Correlation between S and V might vary across environments, resulting in unstable prediction across unknown environments.

Solution: precisely estimate the $\hat{\beta}_{VOLS}$ by removing spurious correlation

Let $\mathbb{E}(\mathbf{V}^T g(\mathbf{S})) = 0$ and $\mathbb{E}(\mathbf{V}^T \mathbf{S}) = 0$.

METHOD

Proposition 1 If \mathbf{X} are mutually independent with mean 0, then $\mathbb{E}(\mathbf{V}^T g(\mathbf{S})) = 0$ and $\mathbb{E}(\mathbf{V}^T \mathbf{S}) = 0$.

Making variable independent by **sample reweighting**:

$$\min_W \sum_{a=1}^{\infty} \sum_{b=1}^{\infty} \|\mathbb{E}[\mathbf{X}_{,j}^{aT} \Sigma_W \mathbf{X}_{,k}^b] - \mathbb{E}[\mathbf{X}_{,j}^{aT} W] \mathbb{E}[\mathbf{X}_{,k}^{bT} W]\|_2^2, \quad (6)$$

Variables decorrelation regularizer

$$\min_W \sum_{j=1}^p \|\mathbb{E}[\mathbf{X}_{,j}^T \Sigma_W \mathbf{X}_{,-j}] - \mathbb{E}[\mathbf{X}_{,j}^T W] \mathbb{E}[\mathbf{X}_{,-j}^T W]\|_2^2 \quad (7)$$

Decorrelated

$$\min_{W, \beta} \sum_{i=1}^n W_i \cdot (Y_i - \mathbf{X}_i \beta)^2 \quad (12)$$

Weighted

$$s.t. \sum_{j=1}^p \|\mathbf{X}_{,j}^T \Sigma_W \mathbf{X}_{,-j} / n - \mathbf{X}_{,j}^T W / n \cdot \mathbf{X}_{,-j}^T W / n\|_2^2 < \lambda_2$$

Regression

$$|\beta|_1 < \lambda_1, \quad \frac{1}{n} \sum_{i=1}^n W_i^2 < \lambda_3,$$

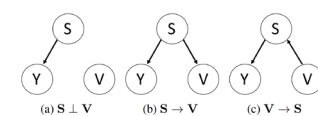
(DWR)

$$\left(\frac{1}{n} \sum_{i=1}^n W_i - 1\right)^2 < \lambda_4, \quad W \geq 0,$$

EXPERIMENTS

Experiments on Synthetic Data

Generating S and V :



Generating Y :

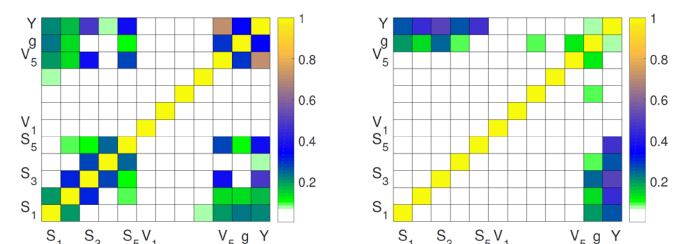
$$Y_{poly} = f(S) + \epsilon = [S, V] \cdot [\beta_S, \beta_V]^T + S_{,1} S_{,2} S_{,3} + \epsilon(17)$$

$$Y_{exp} = f(S) + \epsilon = [S, V] \cdot [\beta_S, \beta_V]^T + e^{S_{,1} S_{,2} S_{,3}} + \epsilon(18)$$

Generating Distributional Shift:

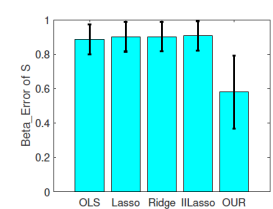
Varying $P(Y|V)$ with bias rate r :

- $r > 1$: positive correlation between V and Y
- $r < 1$: negative correlation between V and Y

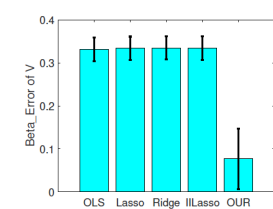


(a) On raw data

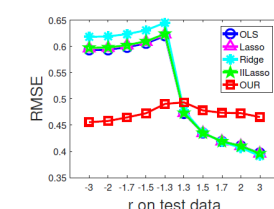
(b) On the weighted data



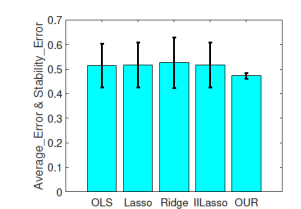
(a) β _Error of S : Mean (green bar) and Variance (black line)



(b) β _Error of V : Mean (green bar) and Variance (black line)



(c) RMSE over all test environments



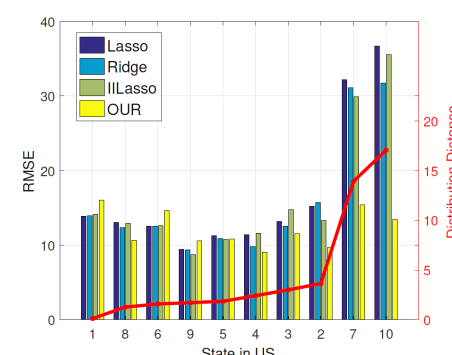
(d) Average_Error (green bar) & Stability_Error (black line)

| Scenario 1: varying sample size n | | | | | | | | | | | | | | | |
|-------------------------------------|-----------------------------|-------|-------|---------|-----------------------------|-------|-------|-------|-----------------------------|--------------|-------|-------|-------|---------|--------------|
| n, p, r | $n = 1000, p = 10, r = 1.7$ | | | | $n = 2000, p = 10, r = 1.7$ | | | | $n = 4000, p = 10, r = 1.7$ | | | | | | |
| | OLS | Lasso | Ridge | ILLasso | Our | OLS | Lasso | Ridge | ILLasso | Our | OLS | Lasso | Ridge | ILLasso | Our |
| β_S _Error | 0.892 | 0.907 | 0.907 | 0.912 | 0.578 | 0.887 | 0.903 | 0.903 | 0.908 | 0.581 | 0.906 | 0.921 | 0.921 | 0.926 | 0.614 |
| β_V _Error | 0.331 | 0.333 | 0.334 | 0.334 | 0.109 | 0.332 | 0.334 | 0.335 | 0.335 | 0.077 | 0.338 | 0.340 | 0.341 | 0.341 | 0.078 |
| Average_Error | 0.509 | 0.511 | 0.511 | 0.511 | 0.476 | 0.514 | 0.516 | 0.527 | 0.516 | 0.473 | 0.526 | 0.528 | 0.531 | 0.528 | 0.480 |
| Stability_Error | 0.084 | 0.086 | 0.086 | 0.086 | 0.012 | 0.090 | 0.092 | 0.103 | 0.092 | 0.012 | 0.104 | 0.105 | 0.108 | 0.106 | 0.015 |

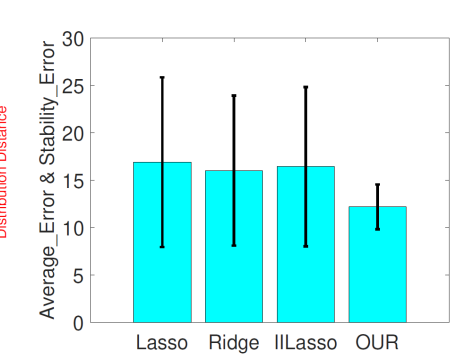
| Scenario 2: varying variables' dimension p | | | | | | | | | | | | | | | |
|----------------------------------------------|-----------------------------|-------|-------|---------|-----------------------------|-------|-------|-------|-----------------------------|--------------|-------|-------|-------|---------|--------------|
| n, p, r | $n = 2000, p = 10, r = 1.5$ | | | | $n = 2000, p = 20, r = 1.5$ | | | | $n = 2000, p = 40, r = 1.5$ | | | | | | |
| | OLS | Lasso | Ridge | ILLasso | Our | OLS | Lasso | Ridge | ILLasso | Our | OLS | Lasso | Ridge | ILLasso | Our |
| β_S _Error | 0.618 | 0.628 | 0.630 | 0.632 | 0.409 | 2.608 | 2.677 | 2.670 | 2.713 | 1.761 | 8.491 | 8.846 | 8.669 | 8.998 | 7.800 |
| β_V _Error | 0.243 | 0.245 | 0.246 | 0.245 | 0.052 | 0.426 | 0.433 | 0.437 | 0.437 | 0.260 | 0.661 | 0.684 | 0.673 | 0.694 | 0.606 |
| Average_Error | 0.486 | 0.487 | 0.487 | 0.487 | 0.476 | 0.523 | 0.527 | 0.539 | 0.529 | 0.480 | 0.532 | 0.540 | 0.537 | 0.543 | 0.490 |
| Stability_Error | 0.058 | 0.059 | 0.060 | 0.059 | 0.010 | 0.116 | 0.121 | 0.134 | 0.123 | 0.014 | 0.138 | 0.148 | 0.145 | 0.153 | 0.073 |

| Scenario 3: varying bias rate r on training data | | | | | | | | | | | | | | | |
|----------------------------------------------------|-----------------------------|-------|-------|---------|-----------------------------|-------|-------|-------|-----------------------------|--------------|-------|-------|-------|---------|--------------|
| n, p, r | $n = 2000, p = 10, r = 1.5$ | | | | $n = 2000, p = 10, r = 1.7$ | | | | $n = 2000, p = 10, r = 2.0$ | | | | | | |
| | OLS | Lasso | Ridge | ILLasso | Our | OLS | Lasso | Ridge | ILLasso | Our | OLS | Lasso | Ridge | ILLasso | Our |
| β_S _Error | 0.618 | 0.628 | 0.630 | 0.632 | 0.409 | 0.887 | 0.903 | 0.903 | 0.908 | 0.581 | 1.232 | 1.249 | 1.245 | 1.257 | 0.651 |
| β_V _Error | 0.243 | 0.245 | 0.246 | 0.245 | 0.052 | 0.332 | 0.334 | 0.335 | 0.335 | 0.077 | 0.441 | 0.444 | 0.443 | 0.445 | 0.119 |
| Average_Error | 0.486 | 0.487 | 0.487 | 0.487 | 0.476 | 0.514 | 0.516 | 0.527 | 0.516 | 0.473 | 0.568 | 0.571 | 0.571 | 0.571 | 0.476 |
| Stability_Error | 0.058 | 0.059 | 0.060 | 0.059 | 0.010 | 0.090 | 0.092 | 0.103 | 0.092 | 0.012 | 0.144 | 0.147 | 0.147 | 0.147 | 0.008 |

Experiments on Real World Data



(a) RMSE v.s. Distribution Distance



(b) Average_Error (green bar) & Stability_Error (black line)

Air quality prediction across different States in U.S.